

## ANALYSIS OF RAPIDEYE'S *RED EDGE* BAND FOR IMAGE SEGMENTATION AND CLASSIFICATION

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### ABSTRACT:

The objective of this study was to evaluate if a multi-resolution segmentation algorithm is sensitive to the RapidEye's *Red Edge* band and its benefits for vegetation mapping using GEOBIA and machine learning. We used a high-resolution multi-spectral RapidEye image taken in June, 2010. This image was segmented with a multiresolution segmentation algorithm (MRIS) using a fine scale parameter (300) and thirteen different weights (from '0' to '100') were assigned to the Red Edge spectral band to evaluate its influence in the segmentation and classification process. Each weight generated a segmented image. Attributes related to spectral information, geometry and texture were calculated for each image segment using the eCognition Developer®. Visual interpretation was performed along with field data to select seven classes (Dense vegetation, Meadow, Mining area, Bare land, Rock outcrop, Urban area and Water). A sample of 800 objects described by its attributes was selected from each segmented image. A decision tree approach based on CART was applied to the samples to select the attributes that provides the best separation among the classes within the scene. An accuracy assessment for the classification using CART was performed to compare the different weights assigned to the Red edge spectral band. Results showed that the Red Edge channel had no significant influence on the segmentation process. The attributes importance rank showed that the index derived from Red Edge channel can be used as input for image classification.

### 1. INTRODUCTION

The use of remotely sensed images for mapping and monitoring land cover had fundamental importance in recent decades, in particular, due the development of new techniques and computer programs that enhanced the analysis and manipulation of these digital products.

Notable advances are being made in land cover mapping due the technological advancement of the recent and upcoming sensors. These advances rely mostly in the introduction of additional bands in multi-spectral sensors. In this study, the wavelength between red and near infrared (690 – 730 nm), called *Red Edge* band, is particularly focused on. Because of its sensitivity to the chlorophyll content of plants, this band is appropriate to vegetation studies. Many studies have been conducted in order to monitor biophysical parameters of vegetation to exploit the importance of the Red Edge for these purposes using spectroradiometry (Chang-Hua et al., 2010; Tian et al., 2011; Ren et al., 2011) and airborne imagery (Schlerf et al., 2009). In the context of spaceborne sensors, Delegido et al. (2011) conducted a study for monitoring green leaf area index and chlorophyll content using the Sentinel-2 Red Edge spectral bands. They have found that Red Edge improved significantly the accuracy of chlorophyll estimation.

RapidEye (Rapideye AG, 2011) represents a constellation of 5 multispectral satellites sensors which provide the *Red Edge* band. These satellites are equally spaced around a sun-synchronous orbit and have a spatial resolution of 5 meters (resampled). Recent studies in land cover mapping suggest that pixel-based approaches have disadvantages for such a high resolution imagery. One alternative to the pixel-based approach is the framework known as GEOBIA – Geographic Object-Based Image Analysis (Hay and Castilla, 2008). Previous

studies have proved its advantages over the well-known pixel-based approach (Ait Belaid et al., 1992; Herrera et al., 2004; YU et al., 2006; Myint et al., 2011). The basic role of this new approach is to merge the adjacent pixels into spectrally homogeneous objects and lead the classification process as the objects being the minimum unit of analysis.

Characteristics within a scene such as spatial resolution and the number of bands can affect the segmentation results as well as the final classification. Consequently, many segmentation algorithms have been developed in recent years, all of them aiming at homogeneous image segments. The multi-resolution image segmentation (MRIS) implemented in eCognition Developer® software is a frequently used algorithm in Earth sciences (Blaschke, 2010). The MRIS offers the possibility to assign different weights to the spectral bands of the image. In this context, the evaluation of the influence of the spectral bands on the process of segmentation might be considered relevant in studies such vegetation mapping and land cover classification. Schuster et al. (2010) evaluated the influence of RapidEye Red Edge channel in the classification accuracy using a pixel-based approach and they have found that the Red Edge led to a slight improvement of the overall accuracy of the classification.

However, no studies exist to evaluate the influence of Red Edge channel in high-resolution multispectral satellites on the image segmentation process using the multiresolution segmentation algorithm in an object-based approach.

#### 1.1 Aims

The objective of this study is to evaluate if multi-resolution segmentation is sensitive to the RapidEye *Red Edge* band and its benefits for vegetation mapping using an object-based

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approach and a machine learning algorithm. Related research questions are:

- 1) Does the Red Edge affect significantly the segmentation process using a multi resolution segmentation algorithm?
- 2) Are land-use classifications based on multi-spectral RapidEye satellite imagery sensitive for the Red Edge spectral band or Red Edge derived indices?
- 3) Does the incorporation of the Red Edge spectral band provide any improvement of the classification accuracy?

## 2. METODOLOGY

### 2.1. Study site and data

The Brazilian Atlantic Rainforest is one of the most important biomes in the country and originally covered approximately 1 million square kilometers within 17 states, representing 16% of the country area (Galindo-Leal and Câmara, 2003). However, the Brazilian Atlantic Rainforest has been under severe pressure since the colonial period due the agricultural cycles and the expansion of cultivated areas. Nowadays, it occupies approximately 98000 square kilometers, or 8% of its original area and is still under strong anthropogenic activities resulting in a high risk of extinction.

The study site is located in the central region of Minas Gerais, Brazil, within the municipalities of Ouro Preto and Mariana (Figure 1). This region holds the largest remnants of Brazilian Atlantic Rainforest within the Minas Gerais state and is considered an important biodiversity hotspot. This region is characterized by a great diversity of environmental settings due its predominant vegetation, urban areas, and mining areas.

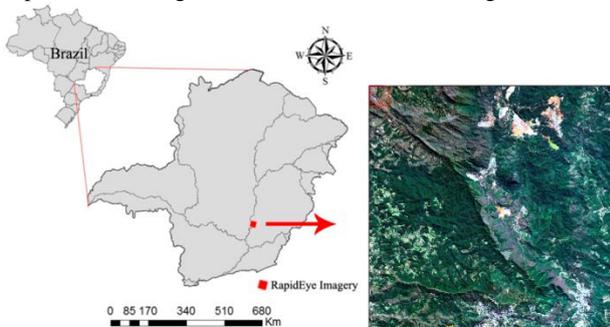


Figure 1. Location of the study area in Minas Gerais, Brazil.

The data used for this study consists of one high-resolution multi-spectral RapidEye imagery obtained from RapidEye AG at standard processing level (orthorectified) by the Minas Gerais state government. The RapidEye imagery was taken in June, 2010.

To evaluate the classification and segmentation results, as well as to select the land cover classes, a visual interpretation of the RapidEye imagery was performed along with the data from Mapeamento da Flora Nativa e dos Reflorestamentos de Minas Gerais (Scolforo and Carvalho., 2006).

### 2.2. Methods

A quick overview of the proposed methodology used in this study can be seen in Figure 2.

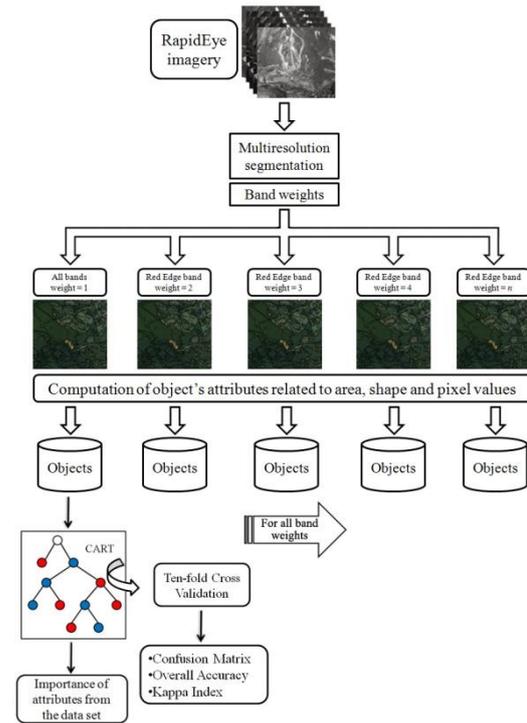


Figure 2. Overview of the proposed methodology.

**2.2.1 Image Segmentation:** The initial RapidEye image analysis included segmenting the image at a relatively fine scale (300) using eCognition Developer® version 8.0. All other parameters were held constant (compactness 0,5 and shape 0,1) since de study focuses exclusively on the influence of the Red, Edge channel on the segmentation and classification processes. Characteristics such as spatial resolution and the number of bands can affect the segmentation results. Many segmentation algorithms have been developed in recent years, all of them aiming at homogeneous image segments. The multi-resolution image segmentation (MRIS) implemented in eCognition Developer® software is a frequently used algorithm in Earth sciences (Blaschke, 2010).

The MRIS offers the possibility to assign different weights to the spectral bands of the image. To evaluate the sensitivity of the MRIS algorithm to the RapidEye Red Edge band, the data set was composed of different segmented images derived using different band weights. Initially, all spectral bands (blue, green, red, Red Edge and near infrared) were equally weighted. Then, different weights were assigned to the Red Edge band to evaluate the impact in the segmentation and class separability. The weights were set as follows: all spectral bands weight with 1 and no weight assigned to the Red Edge (“No Red Edge”), no weight assigned to the other spectral bands and Red Edge assigned with 1 (“Only Red Edge”), all bands equally weighted (“w=1”), all bands weighted with 1 and the Red Edge with 2 (“w=2”) and so forth, thus generating 13 different object-based spatial representations of the image according to the weights assigned to the Red Edge.

**2.2.2 Image Objects Attributes:** Subsequent to the image segmentation, the attributes were calculated for each image segment using the eCognition Developer® 8.0.

A new index that incorporates the Red Edge spectrum was calculated to widen the feature input for the classification process. This new index ranges from the classic NDVI index

with the adaptation to the Red edge channel, according to the Equation 1.

$$NDVI_{RedEdge} = \frac{Red\ Edge - Red}{Red\ Edge + Red} \quad (1)$$

where

Red Edge = reflectance value for the Red Edge channel

Red = reflectance value for the Red channel

Thus, fifty-two attributes were generated using the characteristics shown in Table 3.

Spectral information	Spectral bands
	Band Ratio (RedEdge/NIR*, NDVI and NDVI Red Edge)
Texture GLCM <sub>alldirections</sub>	Brightness
	Entropy
	Homogeneity
	Standard deviation
	Contrast
Geometry	Correlation
	Area
	Roundness
	Compacity
	Boundarie index/Shape
	Length/Width

Table 3. Attributes related to shape, pixel values and texture.

**2.2.3 Data Mining and Variable Importance:** A decision tree approach based on Classification and Regression Tree (Breiman et al., 1984) was used to select the attributes that provide the best separation among the classes within the RapidEye scene. Decision trees are strictly non-parametric and do not require any assumption regarding the data set distribution, presenting several advantages over traditional supervised classification such Maximum Likelihood classification (Friedl and Brodley, 1997).

The CART approach starts with a group of object samples described by a set of attributes – the training objects. This approach relies on splitting the data set into smaller homogeneous sub-sets according to the attributes in each split of the tree. For each weight applied to Red Edge spectral band, the segmentation generated a different number of objects. From these data sets, a sample of approximately 800 objects (from all land cover class) were input to de CART for data mining and classification to evaluate the effects of changing the weight of the Red Edge on the segmentation process and on vegetation mapping. The proportion of objects according to the occurrence of each class within the scene is shown in Table 4.

Bare land	8%
Dense Vegetation	40%
Meadow	20%
Mining area	10%
Rock outcrop	16%
Urban area	5%
Water	1%

Table 4. Attributes related to shape and pixel values.

The CART approach was applied using the WEKA interface freely distributed on the internet and the results were evaluated using a ten-fold Cross-Validation. For further comparison

between the weights, an accuracy assessment for the classification was performed using the Kappa statistic.

### 3. RESULTS AND DISCUSSION

#### 3.1 Image Segmentation

Weights from 1 to 100 were input to the Red Edge band in the multiresolution segmentation algorithm. Segmentation results are shown in Figure 5.

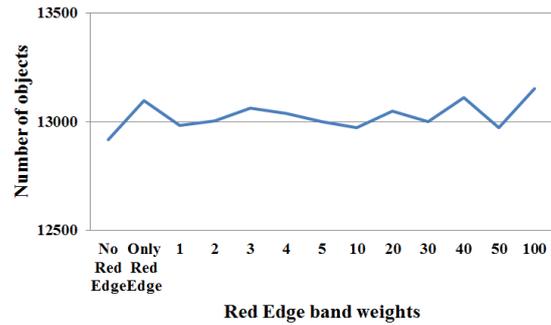


Figure 5. Relationship between the weights assigned to the Red Edge and object count.

The segmentation process showed no significant influence of the Red Edge in the average object count. The differences within the weights assigned to the Red Edge rely mostly on the number of the objects. In particular, the weight “Only Red Edge” has over-segmented most of the land cover classes. Consequently, generating more objects within the classes as it is showed in Figure 6.

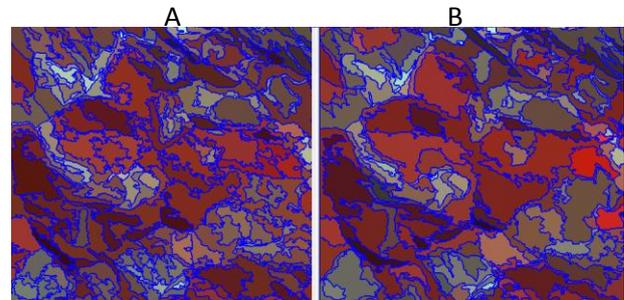


Figure 6. Shape and number of the objects generated by the weights “Only Red Edge” (A) and “No Red Edge” (B). The vegetation is showed in red and maroon due the color composition RGB 521.

#### 3.2 Data Mining and Classification

The results for attribute importance and classification accuracy measures are summarized in Table 7 and 8. From the 52 attributes used in this study, data mining with decision trees indicated the attributes which provided the best class separation.

All the weights which include the Red Edge channel have presented the NDVI and NDVI Red Edge as the best attributes to provide separation among the seven classes. Although the weight ‘No Red Edge’ does not have any participation of the Red Edge channel in the segmentation process, it presented both NDVI and NDVI Red Edge values in the list of best attributes to separate the classes. The presence of NDVI and NDVI Red Edge as the most important attributes to provide separation within the classes can be explained by the fact that ‘Dense

Vegetation' is the predominant land cover class within the area of study. It is known that attributes related to reflectance values in these regions of the electromagnetic spectrum is important to characterize vegetated areas rather than attributes related to

shape of the objects, for example. As shown in the Table 7, the geometry attributes did not heavily participate on the classification process, as the Red Edge did not affect the shape and geometry of the objects.

	No Red Edge	Only Red Edge	W=1	W=2	W=3	W=4	
1	Maximum difference for pixel values	NDVI	NDVI	NDVI	NDVI	NDVI	
2	NDVI	NDVI Red Edge	NDVI Red Edge	NDVI RedEdge	NDVI RedEdge	NDVI RedEdge	
3	NDVI Red Edge	GLCM Correlation for Blue band	Standard deviation for Red Band	GLCM Correlation Blue (all dir.)	Maximum difference for pixel values	Maximum difference for pixel values	
4	Standard deviation for Red Band	Border Index	Standard deviation for Blue Band	Area	RE/NIR	RE/NIR	
5	Standard deviation for Near infrared band	Area	GLCM Correlation for Blue band	GLCM Homogeneity Blue (all dir.)	GLCM Correlation Blue (all dir.)	GLCM Correlation Blue (all dir.)	
	<b>W=5</b>	<b>W=10</b>	<b>W=20</b>	<b>W=30</b>	<b>W=40</b>	<b>W=50</b>	<b>W=100</b>
1	NDVI	NDVI	NDVI	NDVI	NDVI	NDVI	NDVI
2	NDVI RedEdge	NDVI RedEdge	NDVI RedEdge	NDVI RedEdge	NDVI RedEdge	NDVI RedEdge	NDVI RedEdge
3	Maximum difference for pixel values	Maximum difference for pixel values	Maximum difference for pixel values	Maximum difference for pixel values	Maximum difference for pixel values	Maximum difference for pixel values	Maximum difference for pixel values
4	GLCM Correlation Blue (all dir.)	GLCM Correlation Blue (all dir.)	RE/NIR	RE/NIR	RE/NIR	RE/NIR	RE/NIR
5	RE/NIR	RE/NIR	GLCM Correlation Blue (all dir.)	GLCM Correlation Blue (all dir.)	Standard deviation for Red Band	GLCM Correlation Blue (all dir.)	GLCM Correlation Blue (all dir.)

Table 7. Attributes importance for the weights assigned to the segmentation process.

Accuracy Measurements (%)	No Red Edge	Only Red Edge	W=1	W=2	W=3	W=4	
Overall Accuracy	90,93	84,16	90,26	81,38	90,09	89,12	
Kappa	87,79	78,78	87,18	74,88	86,28	85,45	
Dense Vegetation	98,20	98,50	97,90	98,50	99,50	98,20	
Meadow	90,20	78,30	90,90	78,00	88,70	91,80	
Mining Area	85,70	69,20	81,90	63,50	75,00	85,70	
Urban Area	77,80	69,40	74,20	72,70	79,60	75,80	
Rock outcrop	83,90	75,00	85,80	65,40	72,40	68,60	
Bare land	83,30	63,60	81,00	54,90	84,50	79,60	
Water	100,00	100,00	100,00	80,00	66,70	72,70	
	<b>W=5</b>	<b>W=10</b>	<b>W=20</b>	<b>W=30</b>	<b>W=40</b>	<b>W=50</b>	<b>W=100</b>
Overall Accuracy	89,97	89,57	93,18	92,16	91,61	91,63	91,73
Kappa	86,33	86,23	90,60	89,68	89,31	88,96	89,16
Dense Vegetation	97,10	98,20	99,10	99,50	98,90	99,00	98,80
Meadow	92,30	93,50	98,00	96,20	94,30	95,40	94,00
Mining Area	82,60	76,70	84,80	81,80	84,40	77,90	91,70
Urban Area	88,30	73,60	75,60	75,40	78,50	84,40	77,40
Rock outcrop	66,70	72,40	66,70	65,20	76,90	81,00	71,40
Bare land	74,70	84,60	88,40	91,80	89,70	84,40	89,20
Water	84,60	81,80	90,00	84,60	84,20	62,50	60,00

Table 8. Accuracy measures for the weights assigned to the segmentation process.

Cross validation, a measure of misclassification which represents the error rate of the tree, produced an average of 89.67% of overall correct classification for this model adjustment. The classes 'Dense Vegetation' and 'Meadow' showed the highest values of accuracy (Figure 9) due to their spectral characteristics, consequently, being easily separated from the other classes when using vegetation indices such as NDVI and its variation, NDVI Red Edge. However, the different weights did not show any influence on these classes, especially

on the class 'Dense Vegetation', which was not affected by the weight 'No Red Edge'.

The overall accuracy as well as the accuracy for each class did not show any significant increase or decrease trend (Figure 9). The weight 'w=20' presented the highest value of overall accuracy, which means that even higher weights had no influence on the segmentation and classification using CART.

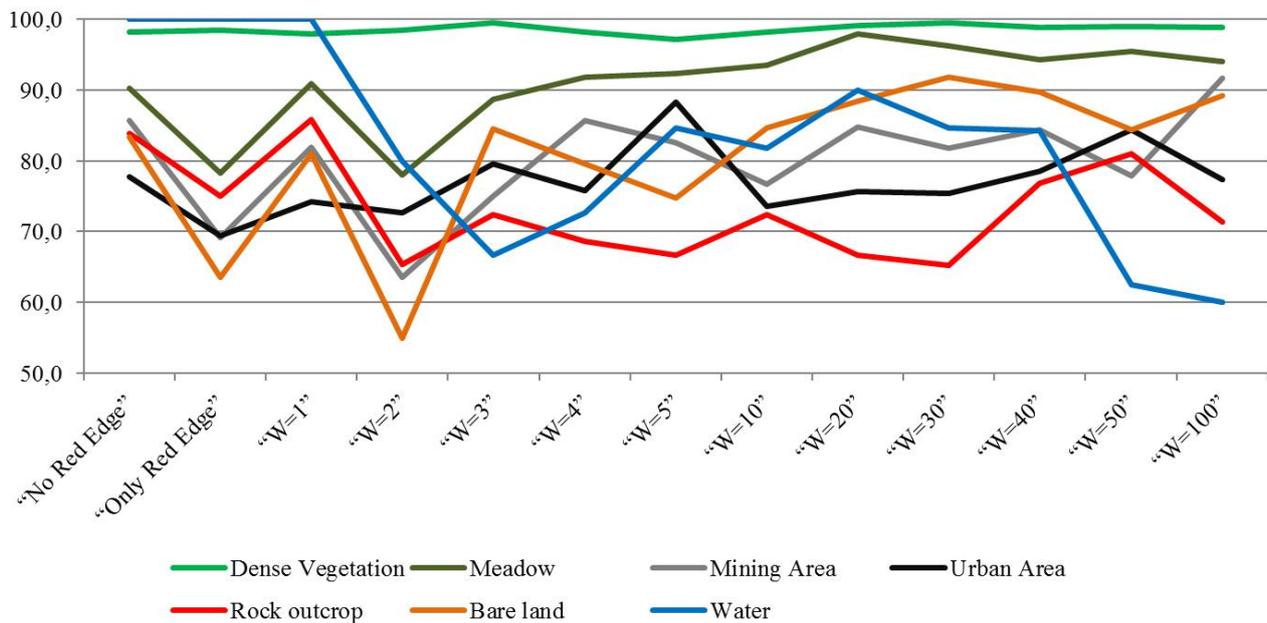


Figure 9. Accuracy measurements for each class.

#### 4. CONCLUSIONS

Results indicated that the Red Edge band had little influence on the segmentation process, as well as on the class separability within the study area using an object-based approach. However, vegetation classes appear to be sensitive to the Red Edge channel and the derived index used in this study. The incorporation of the Red Edge channel presented no improvement on the overall accuracy of the classification.

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